

Conformally Flat Condition (CFC)

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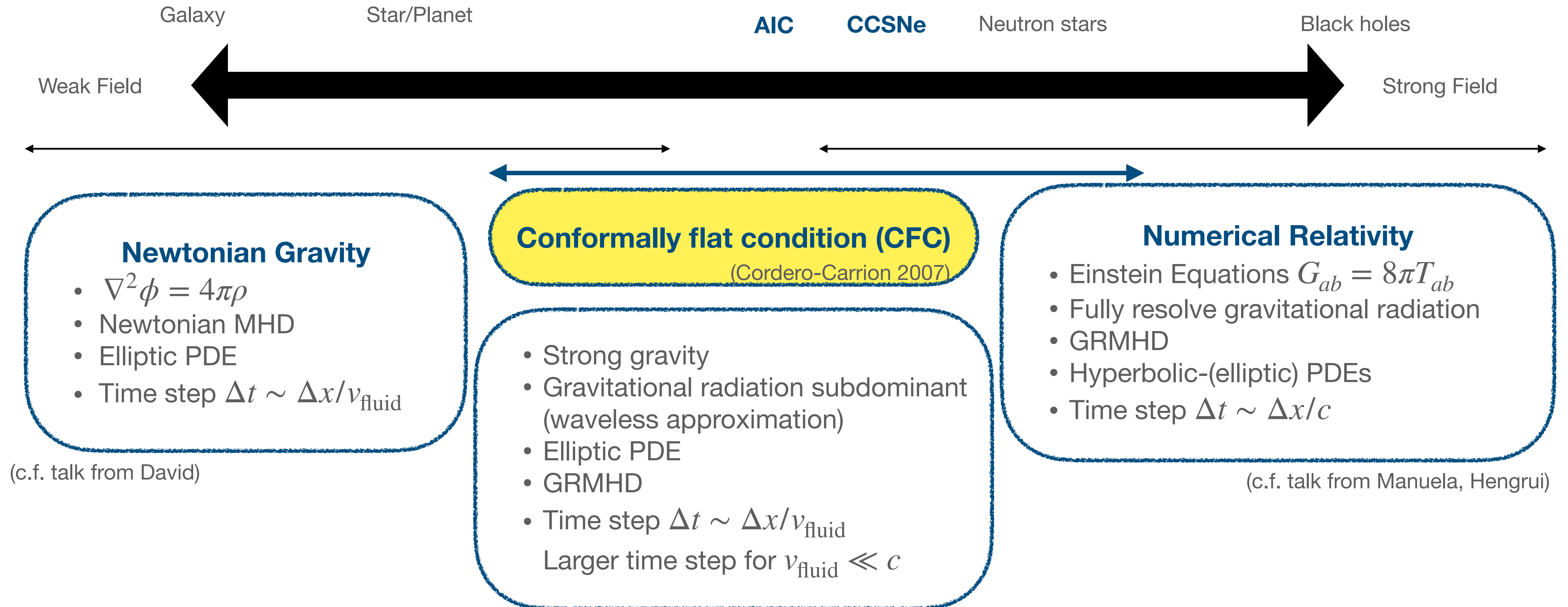
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Self-Gravity



3+1 Decomposition

- normal vector $n^i = (1, -\beta^i)/\alpha \perp$ hypersurface Σ_t

Spatial metric $\gamma_{ab} := g_{ab} + n_a n_b$

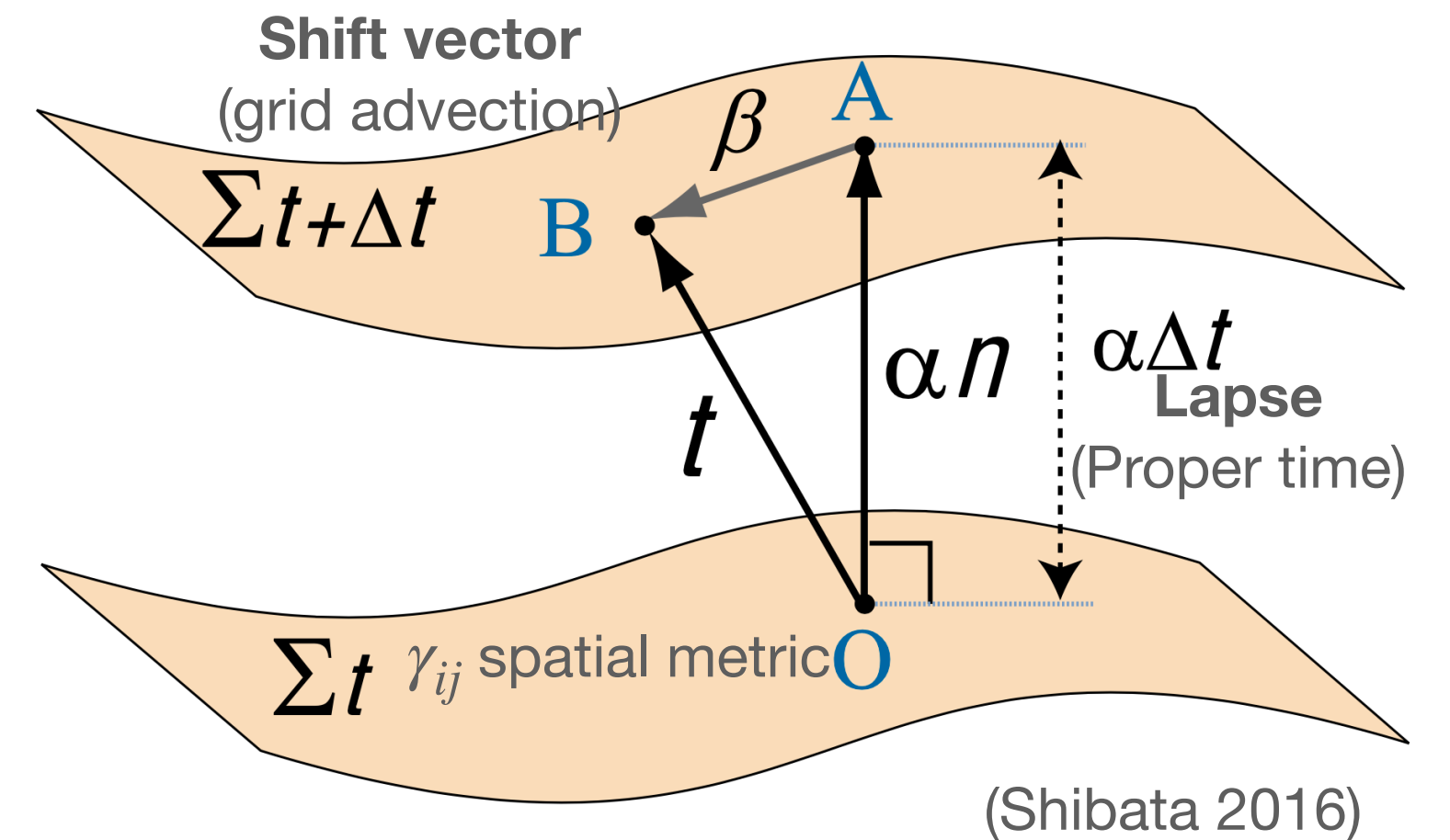
$$ds^2 = -\alpha^2 dt^2 + \gamma_{ij} (dx^i + \beta^i dt) (dx^j + \beta^j dt)$$

- α : **Lapse**

Choice for your **proper time** $\Delta\tau = \alpha\Delta t$ between next slice $\Sigma_{t+\Delta t}$

β^i : **Shift vector**

Choice for your spatial coordinate $x^i \rightarrow x^i - \beta^i \Delta t$ in next slice $\Sigma_{t+\Delta t}$



Gauge condition

- Extrinsic Curvature $K_{ij} \sim \partial_t \gamma_{ij} \Rightarrow$ conjugate pair (γ_{ij}, K_{ij}) similar to (x, p) in Classical Mechanics

- Temporal** projection n^a
Spatial projection γ^a_b

Decompose Stress-Energy Tensor T_{ab}

$$E := n^a n^b T_{ab} \quad \text{Energy}$$

$$S_i := -n^a \gamma^b_i T_{ab} \quad \text{Momentum}$$

$$S_{ij} := \gamma^a_i \gamma^b_j T_{ab} \quad \text{Shear stress Tensor}$$

3+1 Decomposition on Einstein Eq.

$$G_{ab} = 8\pi T_{ab}$$

to obtain evolution equations for (γ_{ij}, K_{ij})

ADM equations

- Arnowitt-Deser-Misner (ADM) equations

D_i :covariance derivative for γ_{ij}

- **Evolution Equations** for (γ_{ij}, K_{ij}) (12 equations)

Weak fields Limit ($\alpha = 1, \beta^i = 0$ + Leading order term)
 $\partial_t \gamma_{ij} = -2K_{ij}$

$$\partial_t \gamma_{ij} = -2\alpha K_{ij} + D_i \beta_j + D_j \beta_i$$

$$\partial_t K_{ij} = \frac{1}{2} \partial_k \partial^k \gamma_{ij} - 8\pi \left(S_{ij} - \frac{1}{2} \gamma_{ij} (S^k_k - E) \right)$$

$$\partial_t K_{ij} = -D_i D_j \alpha + \alpha \left(R_{ij} - 2K_{ik} K^k_j + K K_{ij} \right)$$

$$\Rightarrow \square \gamma_{ij} = 16\pi \left(S_{ij} - \frac{1}{2} \gamma_{ij} (S^k_k - E) \right)$$

$$-8\pi \alpha \left(S_{ij} - \frac{1}{2} \gamma_{ij} (S^k_k - \rho) \right) + \beta^k D_k K_{ij} + K_{ik} D_j \beta^k + K_{jk} D_i \beta^k$$

$$\text{Einstein Eq: } 8\pi \left(T_{ij} - \frac{1}{2} g_{ij} T \right) = R_{ij} \sim \frac{1}{2} \square \gamma_{ij}$$

- **Constraint Equations** (4 equations)

$$G_{00} = 8\pi T_{00} \quad R + K^2 - K_{ij} K^{ij} = 16\pi E \quad \text{Hamiltonian } (\gamma_{ij})$$

$$G_{0i} = 8\pi T_{0i} \quad D_j (K^{ij} - \gamma^{ij} K) = 8\pi S^i \quad \text{Momentum } (K_{ij})$$

Maxwell Equations:

$$\partial_t E = \nabla \times B - 4\pi J$$

$$\partial_t B = -\nabla \times E$$

$$\nabla \cdot E = 4\pi \rho$$

$$\nabla \cdot B = 0$$

∂_t : Constraints between
 $(\gamma_{ij}, \partial_t \gamma_{ij})$

Recast Einstein equations into **Hyperbolic-Elliptic PDEs**
 Evolution equations **conserve** the constraint equations

12 Evolution equations

–4 Gauge conditions

–4 Constraint equations

CFC

~~= 4 dynamical degrees of freedom~~

$(h_+, h_\times, \partial_t h_+, \partial_t h_\times)$

Conformal Transformation

- Factor out the main “**scale**” of spatial metric $\gamma_{ij} = \psi^4 \tilde{\gamma}_{ij}$

ψ : conformal factor

$\tilde{\gamma}_{ij}$: conformal spatial metric

$\tilde{D}_i$: covariance derivative for f_{ij}

- Conformally Flat:** $\tilde{\gamma}_{ij} = f_{ij}$, $\gamma_{ij} = \psi^4 f_{ij}$ (isotropic coordinate)

Schwarzschild BH in isotropic coordinate:

$$ds^2 = - \left(\frac{1 - M/(2r)}{1 + M/(2r)} \right)^2 dt^2 + \left(1 + \frac{M}{2r} \right)^4 (dr^2 + r^2 d\Omega)$$

- Exact** in spherically symmetric spacetime
 $\Rightarrow$ Ideal for systems close to spherical symmetry (CCSNe, NS)

Exercise: Transform TOV solutions (radial gauge)
to isotropic coordinate

- Conformal Transformation on extrinsic curvature $\tilde{A}_{ij} = \psi^{-4} \left(K_{ij} - \frac{1}{3} \gamma_{ij} K \right)$ (traceless part of K_{ij})

- Hamiltonian constraint: $R + K^2 - K_{ij} K^{ij} = 16\pi E$

$$R \sim R_\psi + \tilde{R} \sim \tilde{\Delta} \psi$$

$$\text{Hamiltonian constraint } \tilde{\Delta} \psi = -2\pi \psi^5 E - \frac{1}{8} \psi^5 \tilde{A}_{ij} \tilde{A}^{ij} \quad (\text{set } K = 0 \text{ for the reason shown in the next slide})$$

Maximal-slicing condition

Recall $\partial_t K_{ij} = -D_i D_j \alpha + \dots$

- Consider the trace of $\partial_t K_{ij}$ equation: $\partial_t K = -\Delta \alpha + \alpha \left(K_{ij} K^{ij} + 4\pi (E + S^k_k) \right) + \beta^i D_i K$
- This gives an elliptic equation for α : $\Delta \alpha = -\partial_t K + \alpha \left(K_{ij} K^{ij} + 4\pi (E + S^k_k) \right) + \beta^i D_i K$
- To avoid hyperbolic evolution on the metric, we need to impose **gauge conditions** to enforce equilibrium $\partial_t K = 0$
- Maximal-slicing condition:** $K = 0 = \partial_t K \quad \Rightarrow \Delta \alpha = \alpha \left(A_{ij} A^{ij} + 4\pi (E + S^k_k) \right)$
- Singularity avoidance property:**
freely-falling observer (coordinate) takes **infinite** coordinate time t to reach BH singularity
 $\Rightarrow$ allow stable spacetime evolution with BHs

$$\text{Maximal slicing condition: } \tilde{\Delta} (\alpha\psi) = \alpha\psi \left(\frac{7}{8} \tilde{A}_{ij} \tilde{A}^{ij} + 2\pi (E + 2S^k_k) \right)$$

Conformal Thin Sandwich (CTS)

- We imposed $\tilde{\gamma}_{ij} = f_{ij}$ at $t = 0$. How do we make sure $\tilde{\gamma}_{ij}$ remains flat in time evolution?

- Set $\partial_t \tilde{\gamma}_{ij} = 0$ is a **gauge choice**, not consequence of the Einstein equations

Commonly used in constructing **initial data** for binary neutron stars/BH to enforce quasi-equilibrium $\partial_t \tilde{\gamma}_{ij} = 0$

- Recall the evolution equation: $\partial_t \tilde{\gamma}^{ij} = 2\alpha \tilde{A}^{ij} - \left(\tilde{D}^i \beta^j + \tilde{D}^j \beta^i - \frac{2}{3} \tilde{\gamma}^{ij} \tilde{D}_k \beta^k \right) = 0$

- $\tilde{A}^{ij} = \frac{1}{2\alpha} \left(\tilde{D}^i \beta^j + \tilde{D}^j \beta^i - \frac{2}{3} \tilde{\gamma}^{ij} \tilde{D}_k \beta^k \right) = \frac{1}{2\alpha} (\mathcal{L}\beta)^{ij}$

Conformal Thin Sandwich (CTS)
decomposition

- $\tilde{A}^{ij}$ (6 DoF) $\rightarrow \beta^i$ (3 DoF), we can fix the remaining 3 DoF by **momentum constraint**: $D_j (K^{ij} - \gamma^{ij} K) = 8\pi S^i \sim \tilde{\Delta} \beta^i$

$$\text{CTS decomposition } \tilde{\Delta} \beta^i + \frac{1}{3} \tilde{D}^i \tilde{D}_j \beta^j - 2\alpha \tilde{A}^{ij} \tilde{D}_j \ln(\alpha \psi^{-6}) = 16\pi \alpha f^{ij} S_j$$

The original CFC Scheme

- Isenberg-Wilson-Mathews formulation (the original CFC)
- $\tilde{\gamma}_{ij} - f_{ij} = 0 = \partial_t \tilde{\gamma}_{ij}$, solve for $(\psi, \alpha\psi, \beta^i)$

$$\cdot \tilde{\Delta} \psi = -2\pi E \psi^5 - \frac{1}{8} \tilde{A}_{ij} \tilde{A}^{ij} \psi^5$$

Hamiltonian Constraint

$$\cdot \tilde{\Delta} (\alpha\psi) = \alpha\psi \psi^4 \left[2\pi (E + 2S^k_k) - \frac{7}{8} \tilde{A}_{ij} \tilde{A}^{ij} \right]$$

Maximal Slicing

$$\cdot \tilde{\Delta} \beta^i + \frac{1}{3} \tilde{D}^i \tilde{D}_k \beta^i + \tilde{A}^{ij} \tilde{D}_j \ln (\alpha\psi^{-5}) = 16\pi f^{ij} \alpha S_j$$

Momentum Constraint

$$\cdot \tilde{A}^{ij} = \frac{1}{2\alpha} (\mathcal{L} \beta)^{ij} = \frac{1}{2\alpha} \left(\tilde{D}^i \beta^j + \tilde{D}^j \beta^i - \frac{2}{3} f^{ij} \tilde{D}_k \tilde{D}^k \beta^k \right) \quad \text{CTS } \partial_t \tilde{\gamma}_{ij} = 0$$

- All the equations are coupled together, so we need to iterate until (ψ, α, β^i) converge (**expensive!**).
- Non-linear equation for ψ that suffered from a **non-uniqueness** problem!

Non-uniqueness Problem

(Pfeiffer & York 2005)

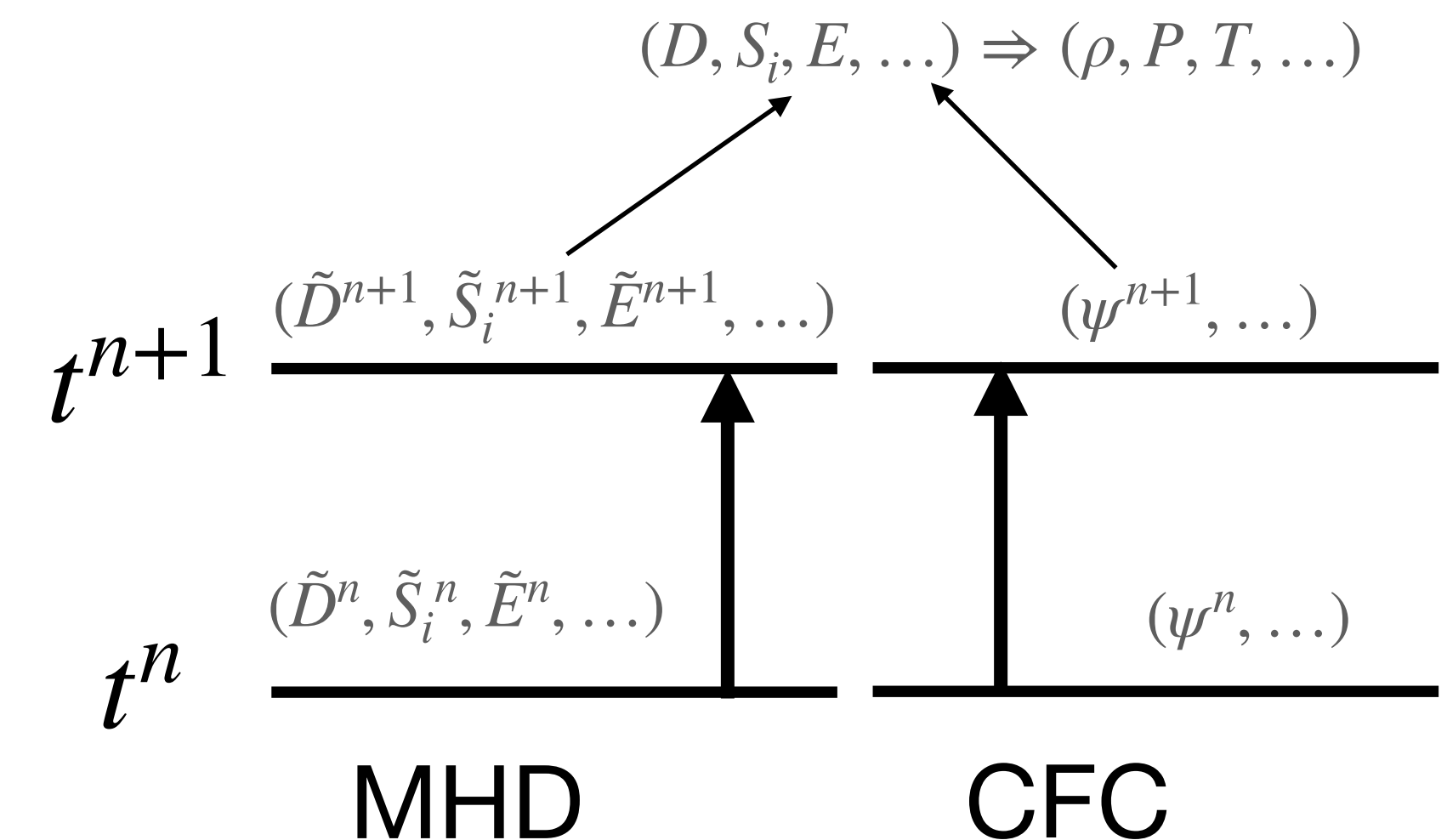
- First found in CTS scheme
- For scalar elliptic equations in form $\Delta u = -hu^p$
- Local uniqueness only for $h \cdot p < 0$

$$\tilde{\Delta}\psi = -2\pi E\psi^5 - \frac{1}{8}\tilde{A}_{ij}\tilde{A}^{ij}\psi^5$$

$$\tilde{\Delta}\psi = -2\pi\tilde{E}\psi^{-1} - \frac{1}{8}\tilde{A}_{ij}\tilde{A}^{ij}\psi^5 \quad \frac{5}{8}\tilde{A}_{ij}\tilde{A}^{ij} > 0$$

The CFC scheme suffered from the **non-uniqueness** problem
We need a reformulation

Conserved variables $\tilde{D} := \sqrt{\gamma}D = \psi^6 D$



CTT decomposition

- Consider another scaling for extrinsic curvature $\hat{A}^{ij} := \psi^{10} A^{ij} \Rightarrow \tilde{A}_{ij} \tilde{A}^{ij} \psi^5 = \hat{A}_{ij} \hat{A}^{ij} \psi^{-7}$
- Reformulate Momentum Constraint $\tilde{D}_j \hat{A}^{ij} = 8\pi f^{ij} \psi^6 S_j = 8\pi f^{ij} \tilde{S}_j$ Solve the non-uniqueness problem!
- Conformal Transverse-Traceless (CTT) decomposition
 $\hat{A}^{ij} = (\mathcal{L}X)^{ij} + \hat{A}_{TT}^{ij}$ where $\tilde{D}_j \hat{A}_{TT}^{ij} = 0$
Longitudinal Transverse
-Traceless
- We can further assume $\hat{A}_{TT}^{ij} = 0$ because
 - For quasi-spherical system, $\hat{A}_{TT}^{ij} \ll \tilde{\gamma}^{ij} - f^{ij} \sim \mathcal{O}(e^2/c^4)$ (Cordero-Carrion 2007)
 - In weak-field regime, $\hat{A}_{TT}^{ij} \sim \partial_t h_+, \partial_t h_\times$ carries information about gravitational radiation

For vector $\mathbf{F} = \nabla \phi + \nabla \times \mathbf{A} \Rightarrow \nabla \cdot \mathbf{F} = \Delta \phi$

$$\text{CTT decomposition: } \tilde{\Delta} X^i + \frac{1}{3} \tilde{D}^i \tilde{D}_j X^j = 8\pi f^{ij} \tilde{S}_j, \quad \hat{A}^{ij} = (\mathcal{L}X)^{ij}$$

$\tilde{\Gamma}^i$ -freezing gauge condition

- In the original CFC, we use CTS decomposition to fix $\tilde{A}^{ij}$ ($\partial_t \tilde{\gamma}^{ij} = 0$)
Now, we use momentum constraints to fix $\hat{A}^{ij} = \psi^{-6} \tilde{A}^{ij}$ (CTT decomposition)
- Can we still impose the equilibrium condition ($\partial_t \tilde{\gamma}^{ij} = 0$)?
Sort of... we still have 3 DoF left (**gauge condition** for β^i !)
- Recall $\partial_t \tilde{\gamma}^{ij} = 0 = 2\alpha\psi^{-6}\hat{A}^{ij} - (\mathcal{L}\beta)^{ij} \Rightarrow$ CTT decomposition: $\tilde{\gamma}^{ij} = \overset{\text{Longitudinal}}{\tilde{\gamma}_L^{ij}} + \overset{\text{Transverse-Traceless}}{\tilde{\gamma}_{TT}^{ij}}$
- Impose **gauge condition** to enforce the **longitudinal** part = 0 ($\tilde{D}_j \tilde{\gamma}^{ij} = 0 = \tilde{\Gamma}^i$)
- Assumption made here: $\partial_t \tilde{\gamma}_{TT}^{ij} = 0 \Leftarrow$ associate with the gravitational wave DoF. Waveless!

$$\tilde{\Gamma}^i\text{-freezing/Minimal Distortion Gauge: } \tilde{\nabla}^2 \beta^i + \frac{1}{3} \tilde{\nabla}^i \left(\tilde{\nabla}_j \beta^j \right) = 16\pi\alpha\psi^{-6} f^{ij} \tilde{S}_j + 2\hat{A}^{ij} \tilde{\nabla}_j (\alpha\psi^{-6})$$

Extended CFC (xCFC)

(Cordero-Carrion 2007)

- Conformally Flat $\tilde{\gamma}^{ij} = f^{ij}$
- Approximation: $\hat{A}_{TT}^{ij} = 0 = \partial_t \tilde{\gamma}_{TT}^{ij}$ (waveless)

- $\tilde{\nabla}^2 X^i + \frac{1}{3} \tilde{\nabla}^i \left(\tilde{\nabla}_j X^j \right) = 8\pi f^{ij} \tilde{S}_j$ Momentum Constraint

- $\tilde{\nabla}^2 \psi = -2\pi \tilde{E} \psi^{-1} - \frac{1}{8} \hat{A}_{ij} \hat{A}^{ij} \psi^{-7}$ Hamiltonian Constraint

- $\tilde{\nabla}^2 (\alpha \psi) = (\alpha \psi) \left[2\pi (\tilde{E} + 2\tilde{S}^k_k) \psi^{-2} + \frac{7}{8} \hat{A}_{ij} \hat{A}^{ij} \psi^{-8} \right]$ Maximal Slicing

- $\tilde{\nabla}^2 \beta^i + \frac{1}{3} \tilde{\nabla}^i \left(\tilde{\nabla}_j \beta^j \right) = 16\pi \alpha \psi^{-6} f^{ij} \tilde{S}_j + 2\hat{A}^{ij} \tilde{\nabla}_j (\alpha \psi^{-6})$ Minimal Distortion

- **Non-uniqueness** problem solved
- No downstream dependence. We can just solve the metric in **consecutive** order.
- Always satisfy **constraints** and some **equilibrium** conditions for metric.
⇒ Every step is an **initial data** for z4c

Solving Vector Equations

- Solve Vector equations for X^i and β^i : $\nabla^2 V^i + \frac{1}{3} \nabla^i \left(\nabla_j V^j \right) = \mathcal{S}^i$
- Three equations for V^x, V^y, V^z coupled via $\nabla^i \left(\nabla_j V^j \right)$
- Contain mixed derivatives (e.g. $\partial_x \partial_y X^i$)
 $\Rightarrow$ require edge ghost cells communication.
- Decompose V^i into a vector P^i + a scalar η (Oohara 1997, Shibata 1999)

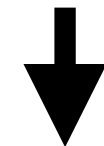
$$V^j = f^{ij} \left[\frac{7}{8} P_i - \frac{1}{8} \left(\partial_i \eta + x^k \partial_i P_k \right) \right]$$

Decompose vector equations: $\nabla^2 V^i + \frac{1}{3} \nabla^i \left(\nabla_j V^j \right) = \mathcal{S}^i \Rightarrow$

$$\begin{aligned} \nabla^2 P^i &= \mathcal{S}^i \\ \nabla^2 \eta &= -x_i \mathcal{S}^i \end{aligned}$$

Task flows for CFC

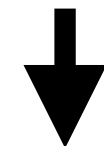
Update GRMHD conservative variables ($\tilde{D}, \tilde{S}_i, \tilde{\tau}, \dots$)



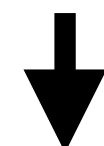
Solve for X : $\nabla^2 X^i + \frac{1}{3} \nabla^i (\nabla_j X^j) = 8\pi f^{ij} \tilde{S}_j$



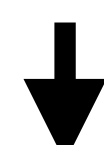
Reconstruct $\hat{A}^{ij}$: $\hat{A}^{ij} = \nabla^j X^i + \nabla^i X^j - \frac{2}{3} f^{ij} \nabla_k X^k$



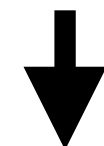
Solve for ψ : $\nabla^2 \psi = -2\pi \tilde{E} \psi^{-1} - \frac{1}{8} \hat{A}_{ij} \hat{A}^{ij} \psi^{-7}$



Obtain ($D, S_i, \tau, \dots$) $\Rightarrow$ Primitive recovery ($\rho, P, T, \dots$) $\Rightarrow$ Evaluate $\tilde{S}$



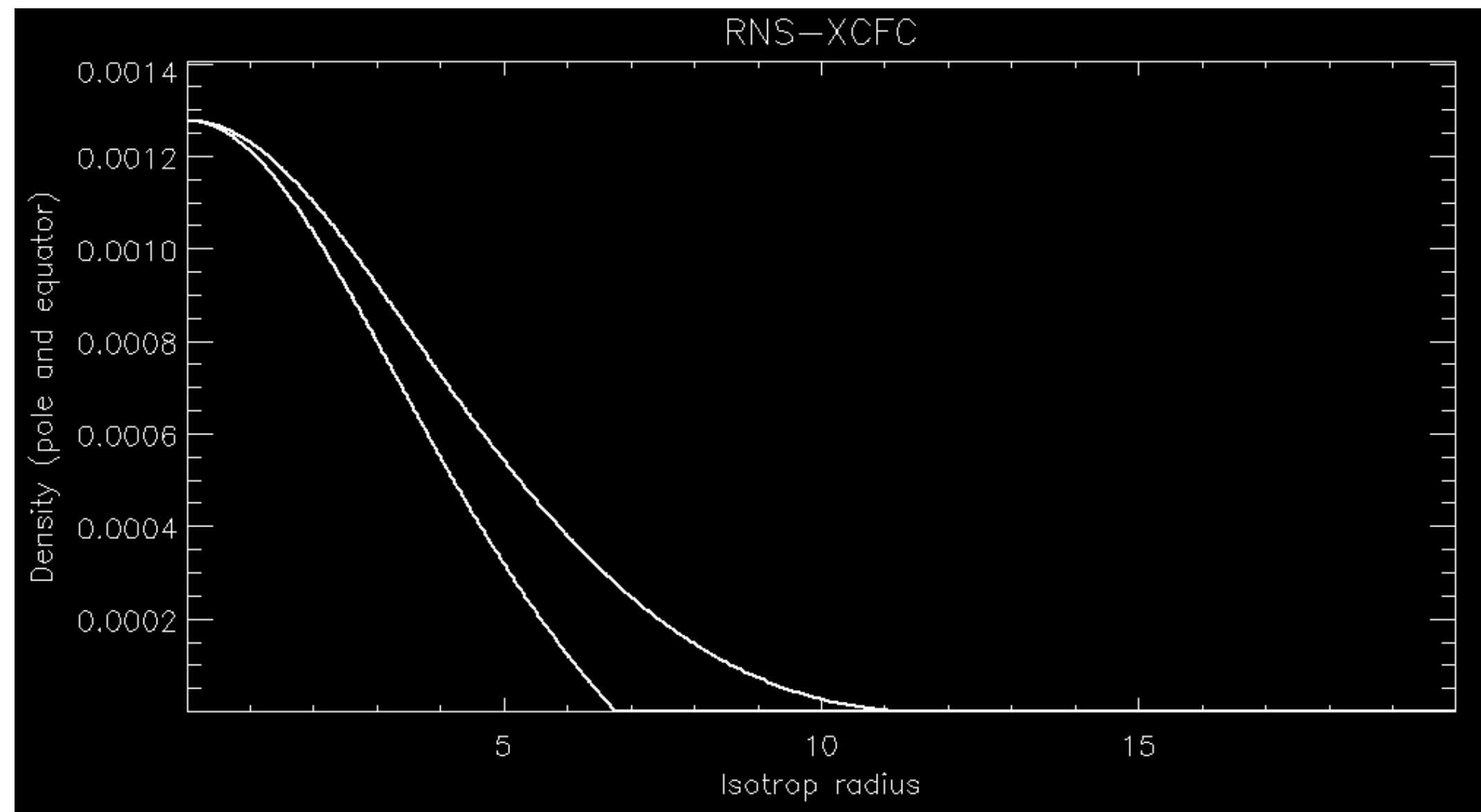
Solve for α : $\nabla^2 (\alpha \psi) = (\alpha \psi) \left[2\pi (\tilde{E} + 2\tilde{S}) \psi^{-2} + \frac{7}{8} \hat{A}_{ij} \hat{A}^{ij} \psi^{-8} \right]$



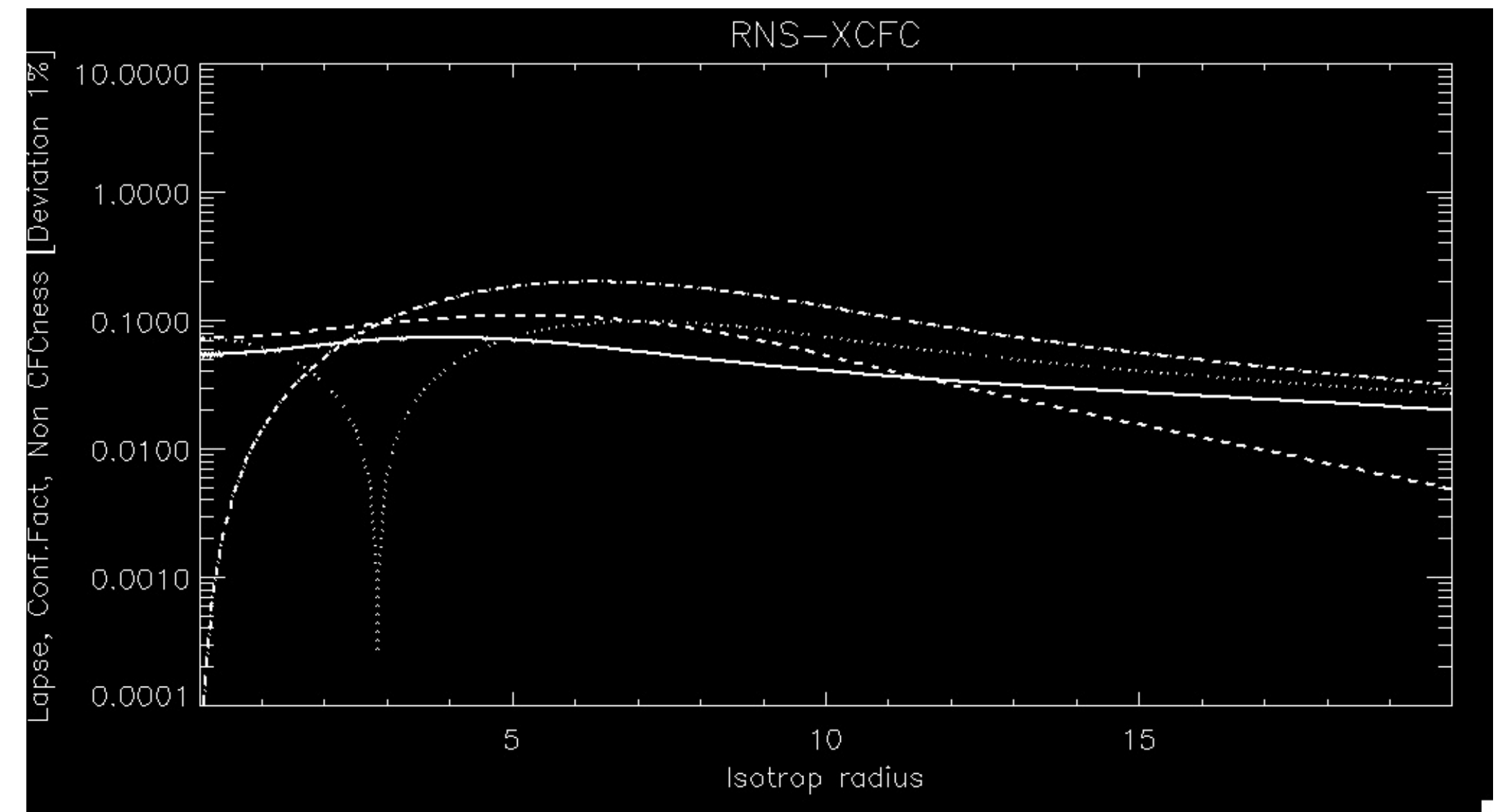
Solve for β^i : $\nabla^2 \beta^i + \frac{1}{3} \nabla^i (\nabla_j \beta^j) = 16\pi \alpha \psi^{-6} f^{ij} \tilde{S}_j + 2\tilde{A}^{ij} \nabla_j (\alpha \psi^{-6})$

Application: Neutron Star

- Comparison between **initial data** from **XNS** (xCFC) and **RNS** (full GR) for rotating NS



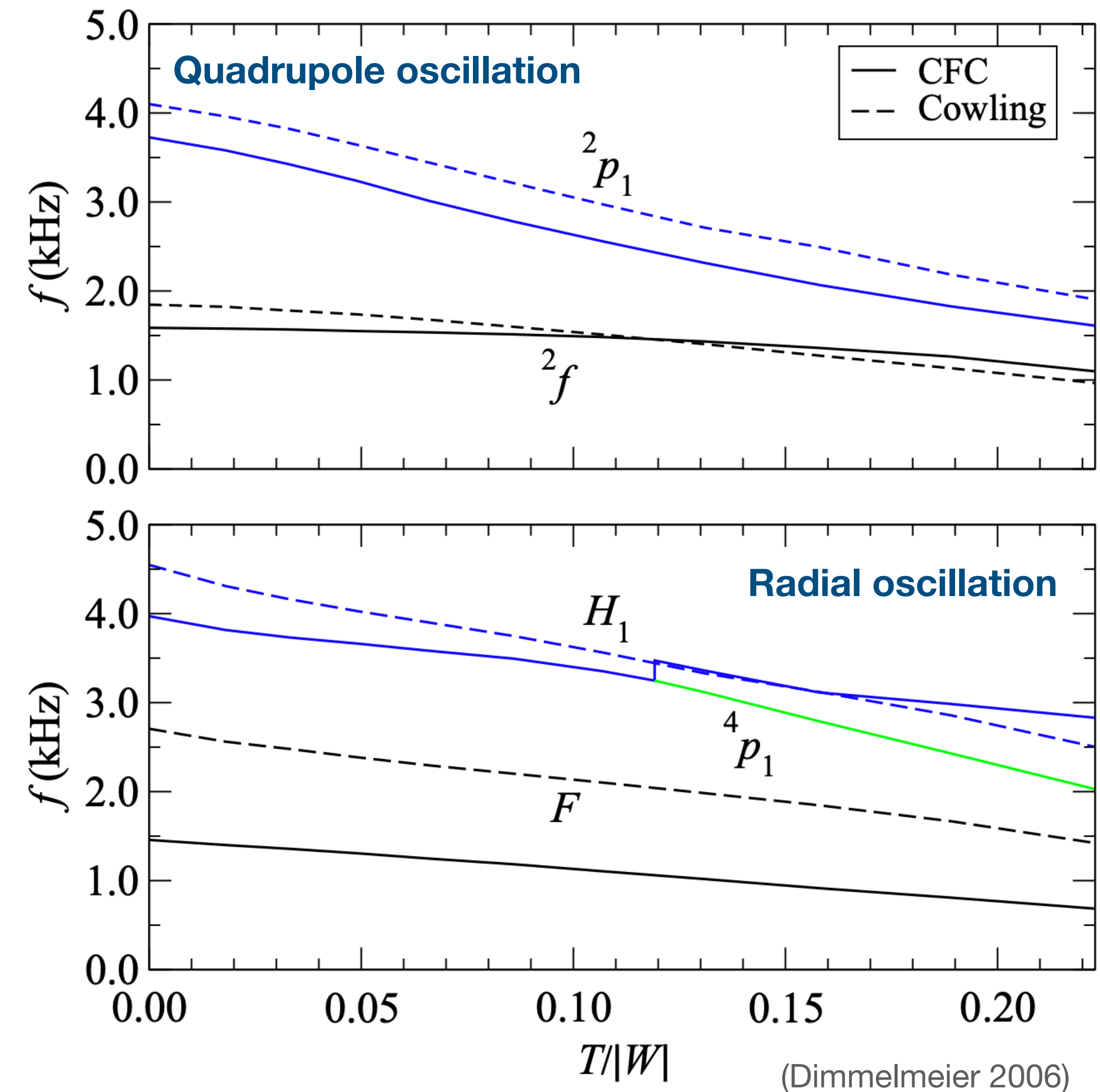
Polar and equatorial density profile
XNS (dash) vs RNS (solid)



Metric quantities deviate by $\lesssim 0.1\%$

Application: Neutron Star oscillation

- Neutron star oscillation mode in xCFC vs Cowling (stationary spacetime)
- Deviation up to a factor of 2
- Solving self-gravity is **necessary**
⇒ Important for CCSNe simulations to estimate GW frequency from PNS.



xCFC in AthenaK (Upcoming)

- Summer school is about initiating projects on AthenaK
Start the development a few days ago (**Claude** assisted) c.f (Hengrui talk on AI)
- Thanks to David's multigrid solver and gravity module.

- Evolving a TOV star
(mesh block 32^3)
- 100% Not **bug-free**
- **TODO:** debug & testing

